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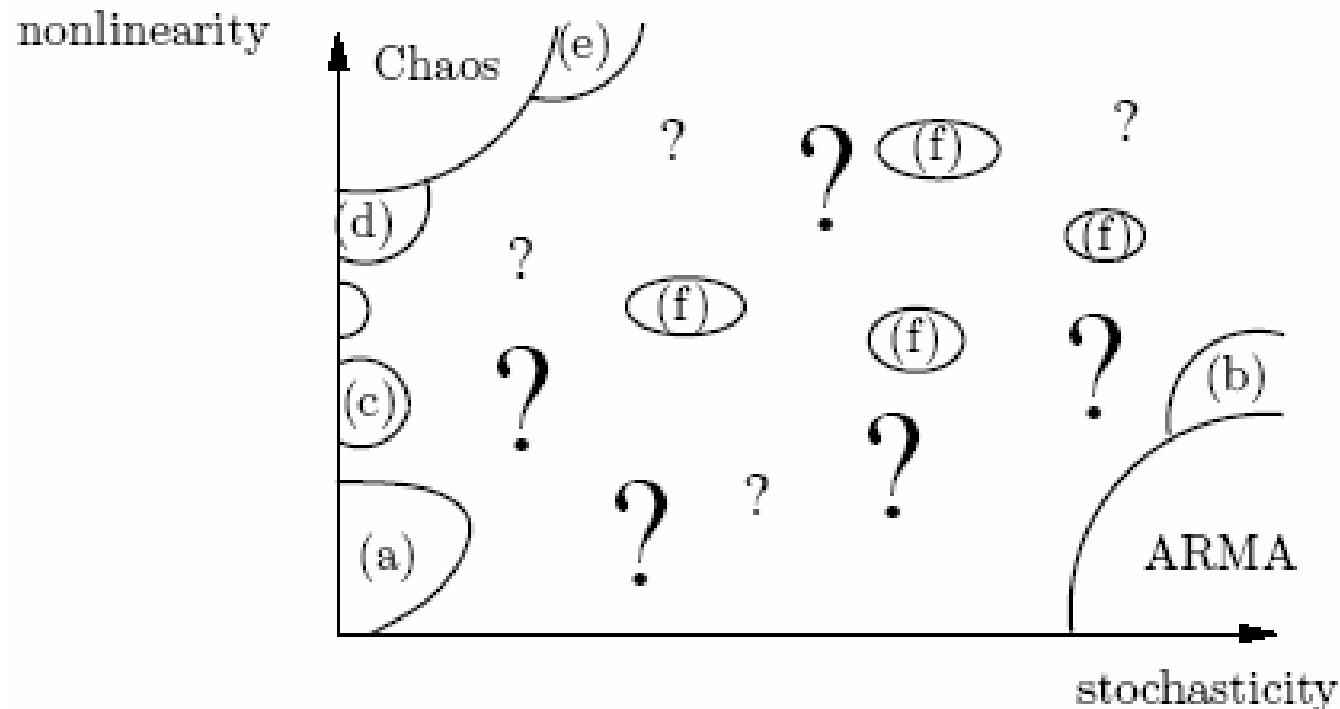
# Towards Online Monitoring of the Changes in Signal Modality: The Degree of Sparsity

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# Signal Modality – General Perspective

Notice the difference between **Signal Nonlinearity** and **System Nonlinearity**

**Deterministic vs. Stochastic nature or Linear vs. Nonlinear nature**



Change in signal modality can indicate e.g. health hazard (fMRI, HRV)

# Challenges in Signal Modality Characterisation

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- Changes in the signal nature between (e.g. linear and nonlinear) can reveal **information** which is critical (e.g. health conditions);
- Existing algorithms based on **hypothesis testing** and operate in a **batch manner**;
- Other methods based on comparing outputs of **two adaptive filters of different kind**  $\Rightarrow$  **choice of many parameters**
- These filters **do not co-operate**  $\Rightarrow$  simple test but *non-unique solution*.

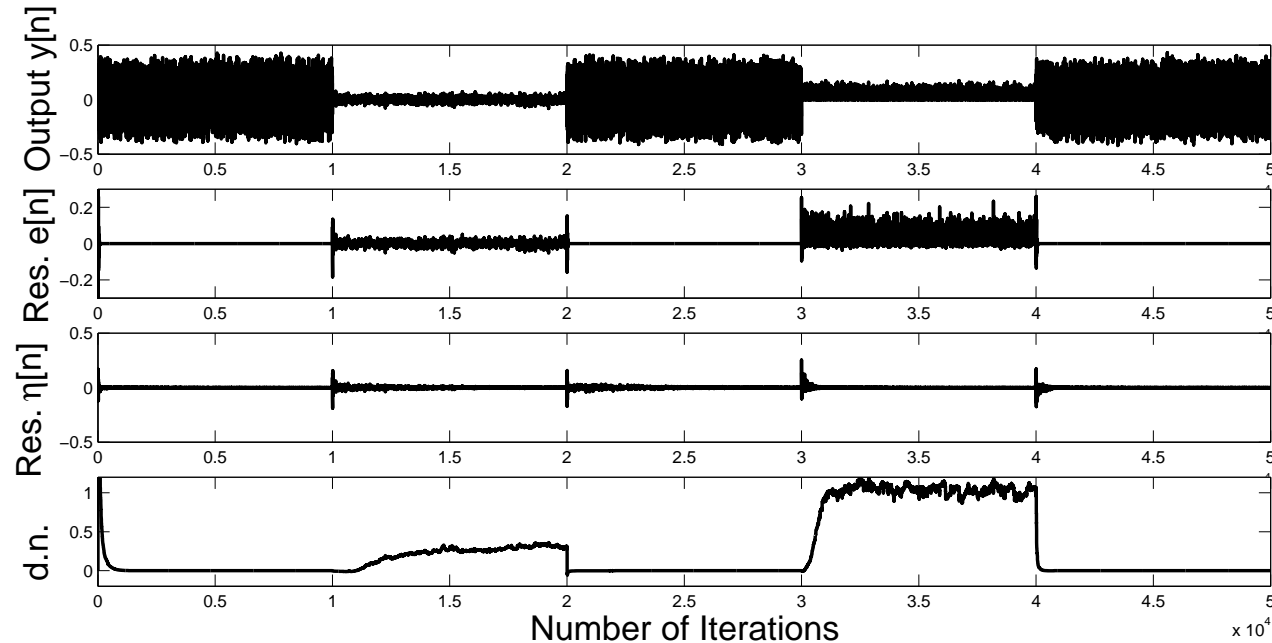
**Our aim:- on-line signal modality characterisation for real-world problems**

**Benefits:- Synergy between the filters, existence and uniqueness of solution**

# Existing Parametric Methods

**Illustration:-** Run independently e.g. 3rd order Volterra and LMS FIR filter

Alternate 10,000 “linear” and 10,000 “nonlinear” samples



- i) Relies on a parametric model to effectively model the system;
- ii) **Slow response**;
- ii) Ability to detect changes in nonlinearity particularly suited to the Volterra model.

# Hybrid Filters

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## Key properties:-

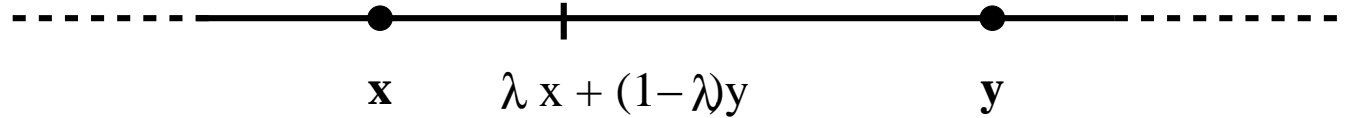
- Multiple individual adaptive subfilters operating in parallel;
- Subfilters feed into a mixing algorithm which produces the single output of the filter;
- Mixing algorithm is also adaptive and combines the outputs of the subfilters (**collaboration, synergy for two different filters**);

## Advantages:-

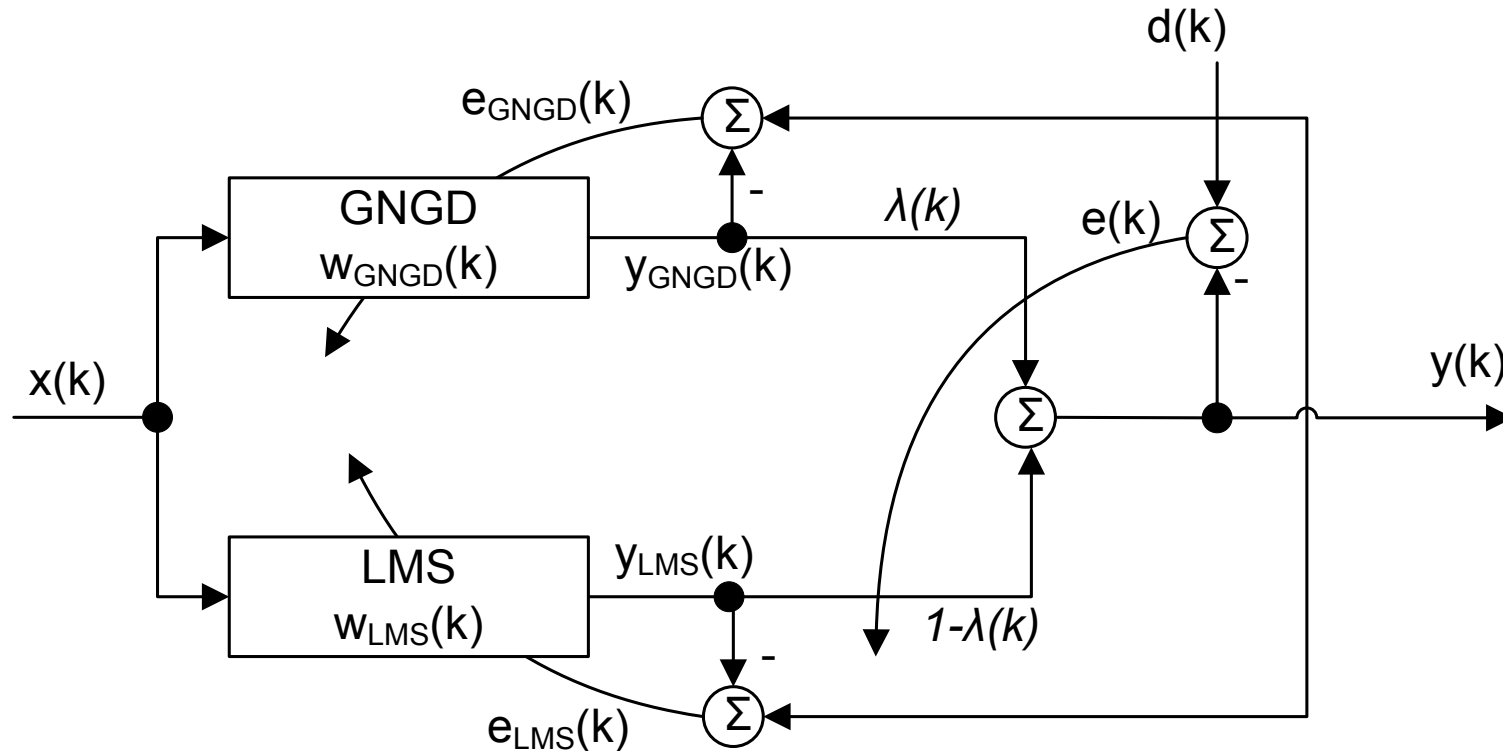
- When in “filtering mode”, improved performance over the individual constituent filters;
- One effect of this mixing algorithm is that it can give an indication of which filter is currently responding to the input signal most effectively;
- By selecting algorithms which are suitable for either linear or nonlinear signals  $\Rightarrow$  the mixing algorithm can adapt according to fundamental properties of the input signal.

# Convex Hybrid Filtering Configuration - Nonlinearity

Virtues of Convex Combination ( $\lambda \in [0, 1]$ )

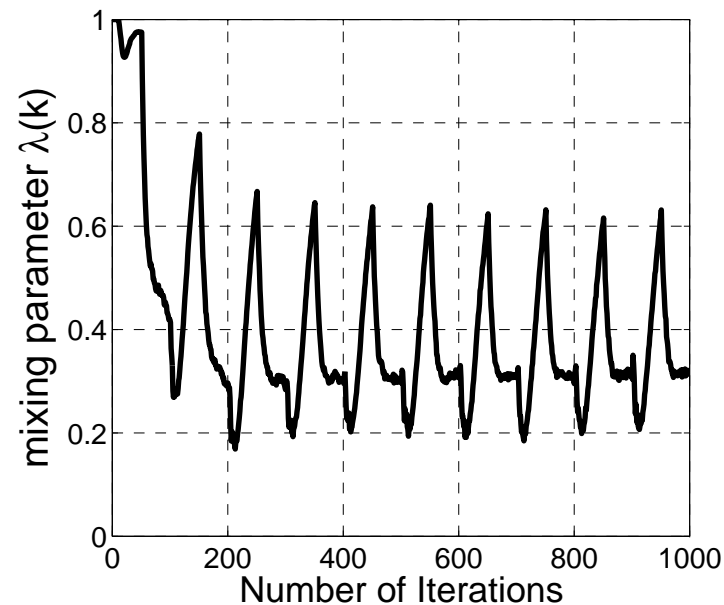
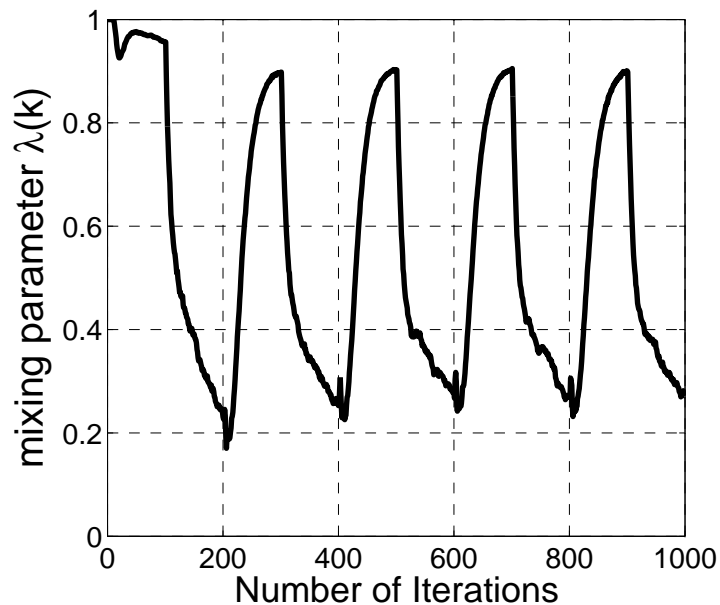


Convexity  $\Rightarrow$  existence and uniqueness of solution



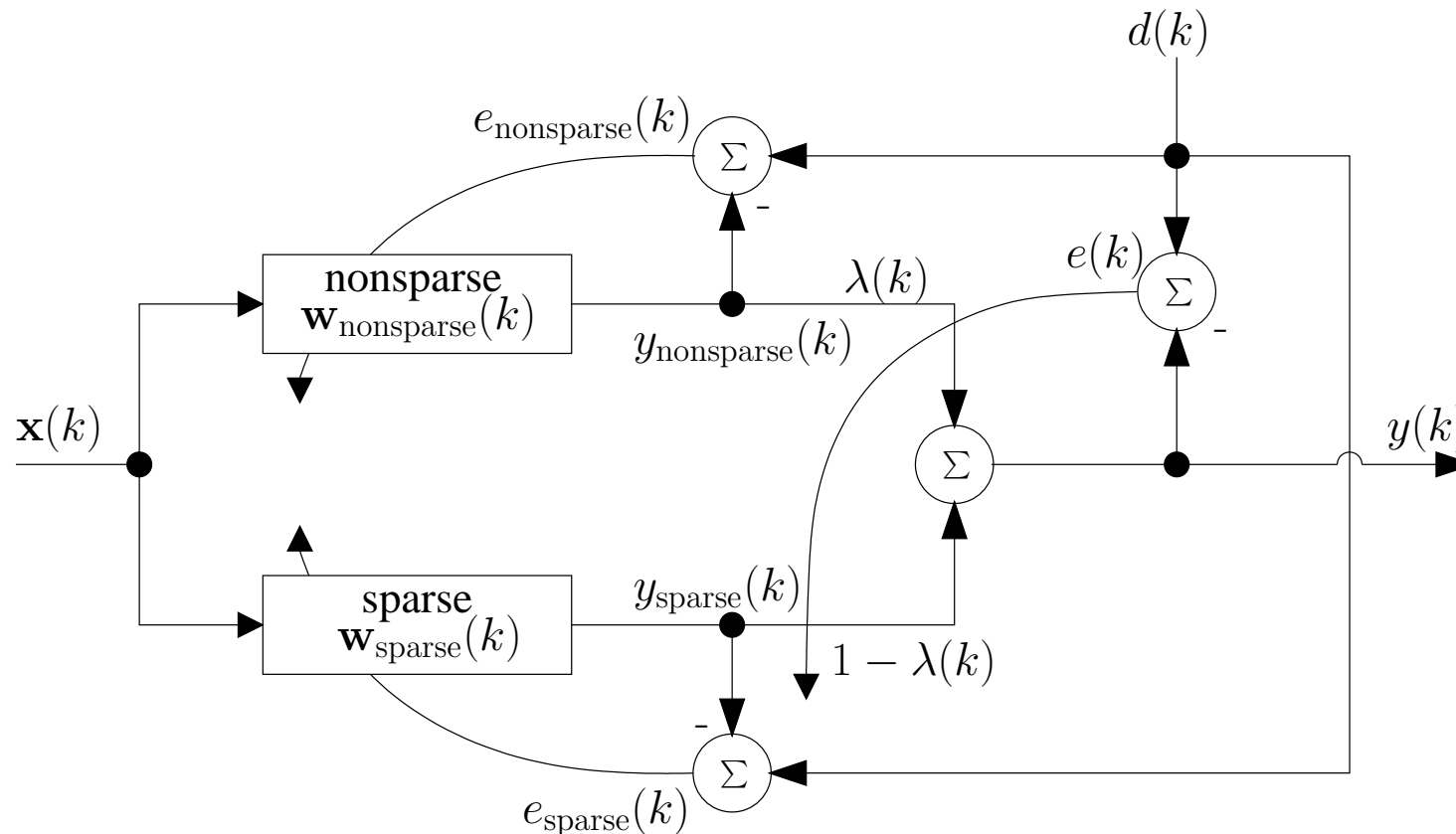
# Tracking Capability

The hybrid filter was presented with an input signal which alternated between linear (AR4) and nonlinear (Narendra III) every 100 and every 50 samples



- When alternating every 50 samples a small anomaly in the values of  $\lambda$  occurs immediately following the change in input signal from nonlinear to linear;
- Not an issue for less regular alternations or if there is a more natural progression from “linear” to “nonlinear”

# Sparse/Nonsparse Configuration

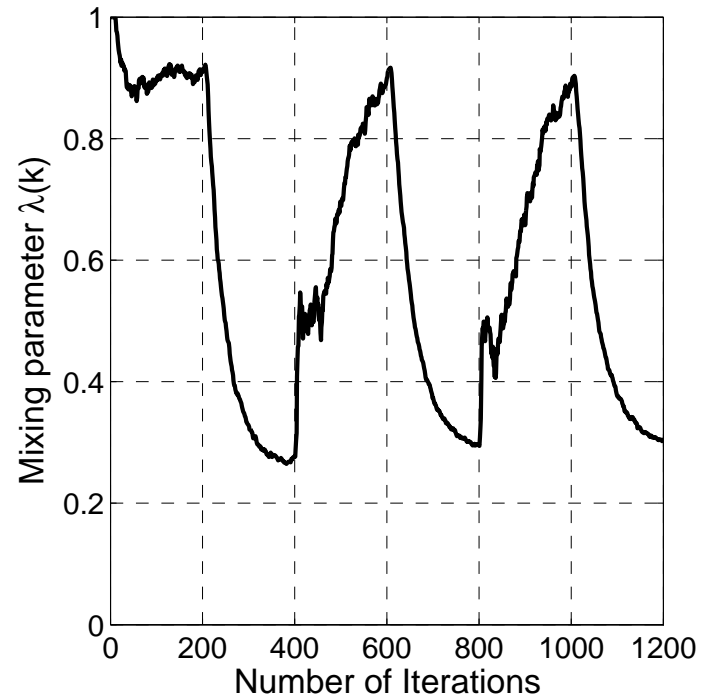
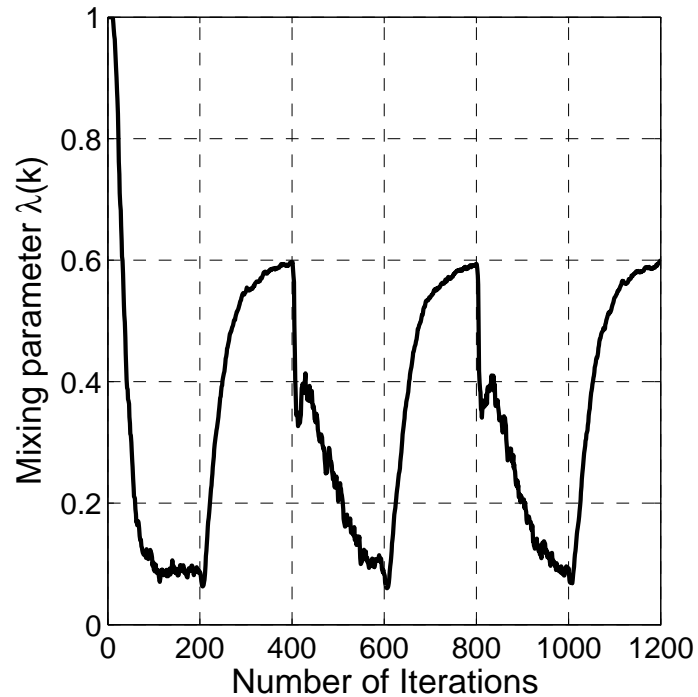


- For the nonsparse filter the NLMS proved a better choice than the LMS due to its faster convergence speed and improved tracking capabilities
- For the sparse filter the PNLMS and SSLMS were compared



# PNLMS in hybrid filter

Not suited for Hybrid Filter



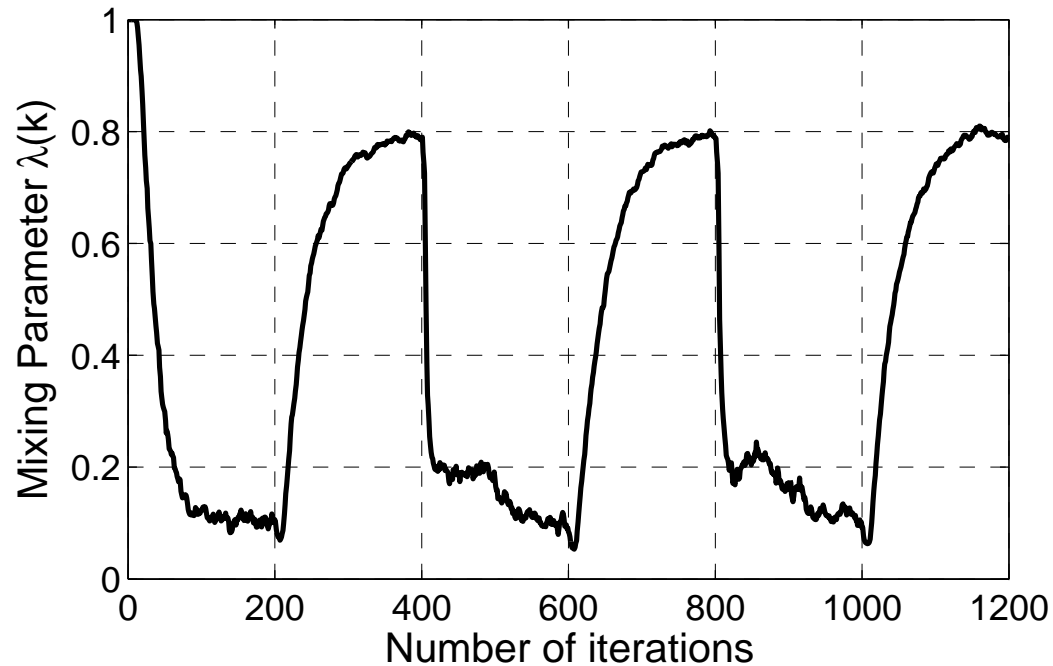
i) Too similar to NLMS

ii) Can span whole range between sparse and nonsparse

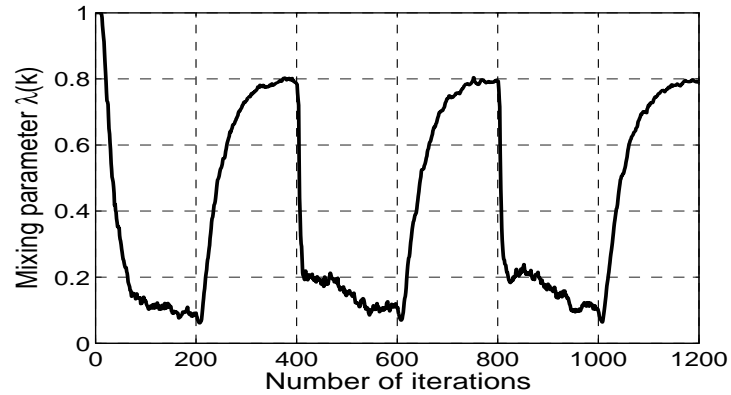
# SSLMS in hybrid filter

The same experiment, with PNLMS replaced with SSLMS

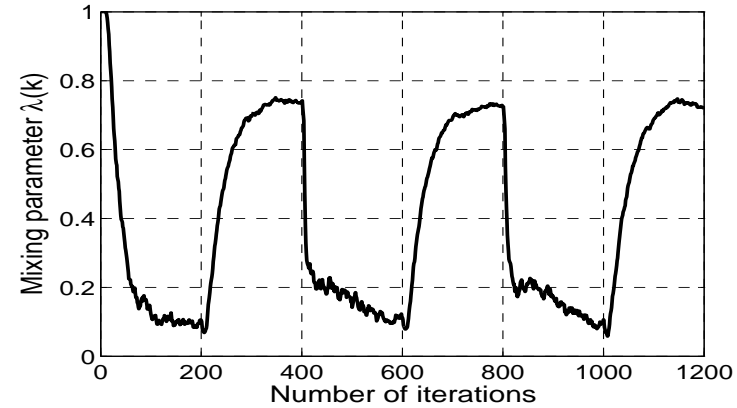
$$\begin{aligned}y(k) &= \mathbf{x}^T(k)\mathbf{w}(k) \\e(k) &= d(k) - y(k) \\ \mathbf{w}(k+1) &= \mathbf{w}(k) + \mu (|\mathbf{w}(k)| + \varepsilon) e(k)\mathbf{x}(k)\end{aligned}$$



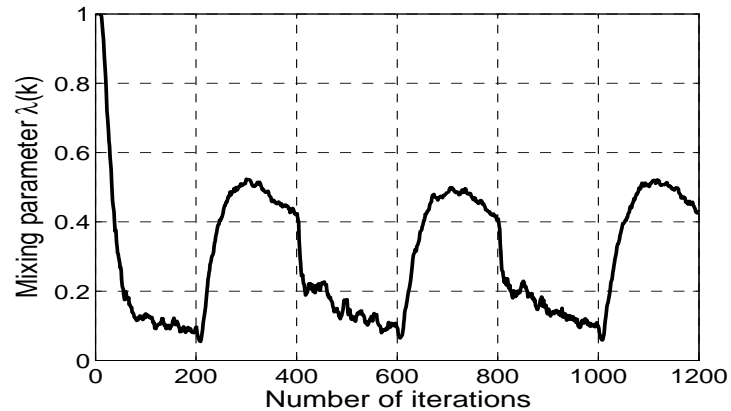
# Sparse hybrid with noise



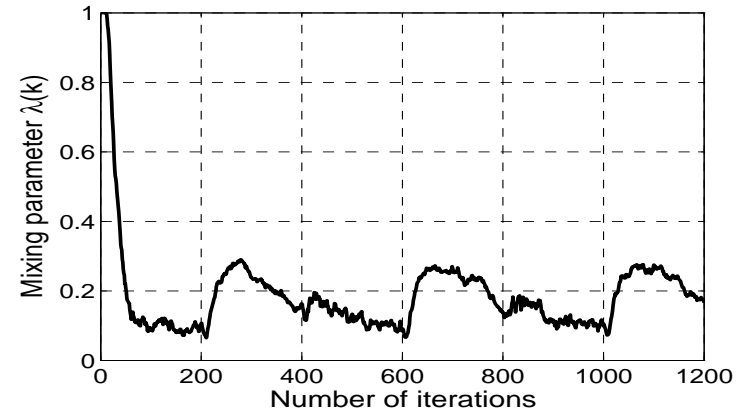
(a) SNR=30dB



(b) SNR=20dB



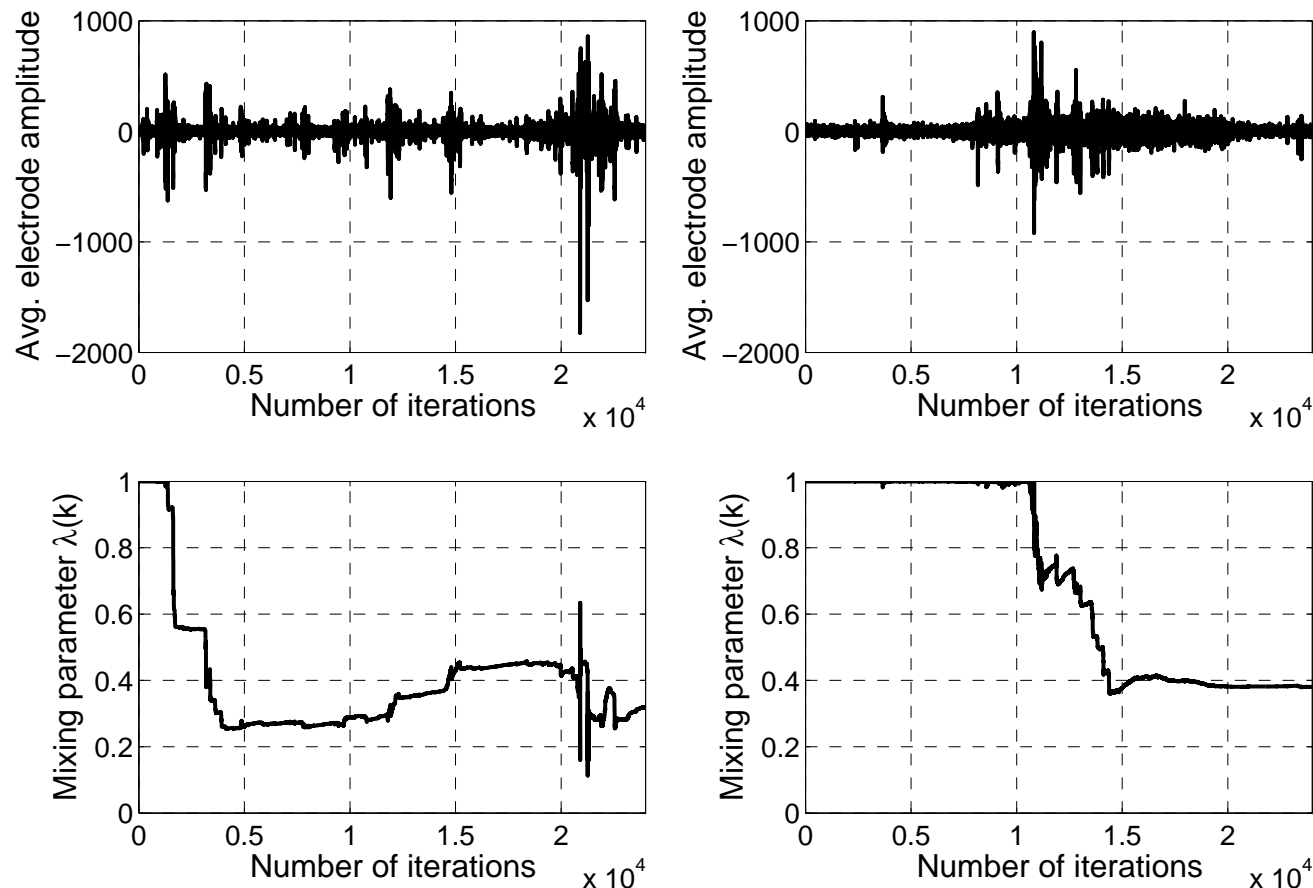
(c) SNR=10dB



(d) SNR=5dB

# Real-World Applications:- Epileptic Seizure Data

EEG data showing the onset of epileptic seizures has been observed



The proposed approach effectively detects changes in the nature of the EEG signals

# Conclusions

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- Novel approach to identify changes in the modality of a signal;
- Convex combination of two adaptive filters for which the transient responses are significantly different, in order to exploit the different performance capabilities of each;
- Collaborative adaptive signal processing approach, based on synergy between the constitutive filters;
- The evolution of the adaptive convex mixing parameter  $\lambda$ , helps determine which filter is more suited to the current input signal dynamics, and thereby gain information about the nature of the signal;
- The analysis and simulations illustrate that there is significant potential for the use of this method for online tracking of some fundamental properties of the input signal.